

In Gaze We Trust: Comparing Eye Tracking, Self-report, and Physiological Indicators of Dynamic Trust during HRI



Yinsu Zhang¹, Aakash Yadav¹, Sarah Hopko², Ranjana Mehta¹

¹Department of Industrial & Systems Engineering, University of Wisconsin-Madison, WI, USA

²Department of Industrial & Systems Engineering, Texas A&M University, TX, USA35

BACKGROUND

Trust has been shown to affect outcomes of human-robot interactions (HRI) [1]. Human operators can over-trust and misuse the system by not providing sufficient monitoring, causing accidents, and it is also possible for them to disuse the robot due to under-trusting [2, 3]. Thus, it is important to continuously measure and understand the dynamics of shared space HRI trust and how trust is built, breached, and recovered.

OBJECTIVE

Assess if eye tracking or physiological indicators offer greater sensitivity in capturing dynamic trust during HRI than the commonly used trust self-reports

METHODS

- 38 participants (18 males, 22 females), mean age 25.88 ± 5.27 years
- Universal Robots collaborative-robot (UR10; Universal Robots, Denmark)
- **Ten 100% reliable trials, then ten 76% reliable trials to manipulate trust**



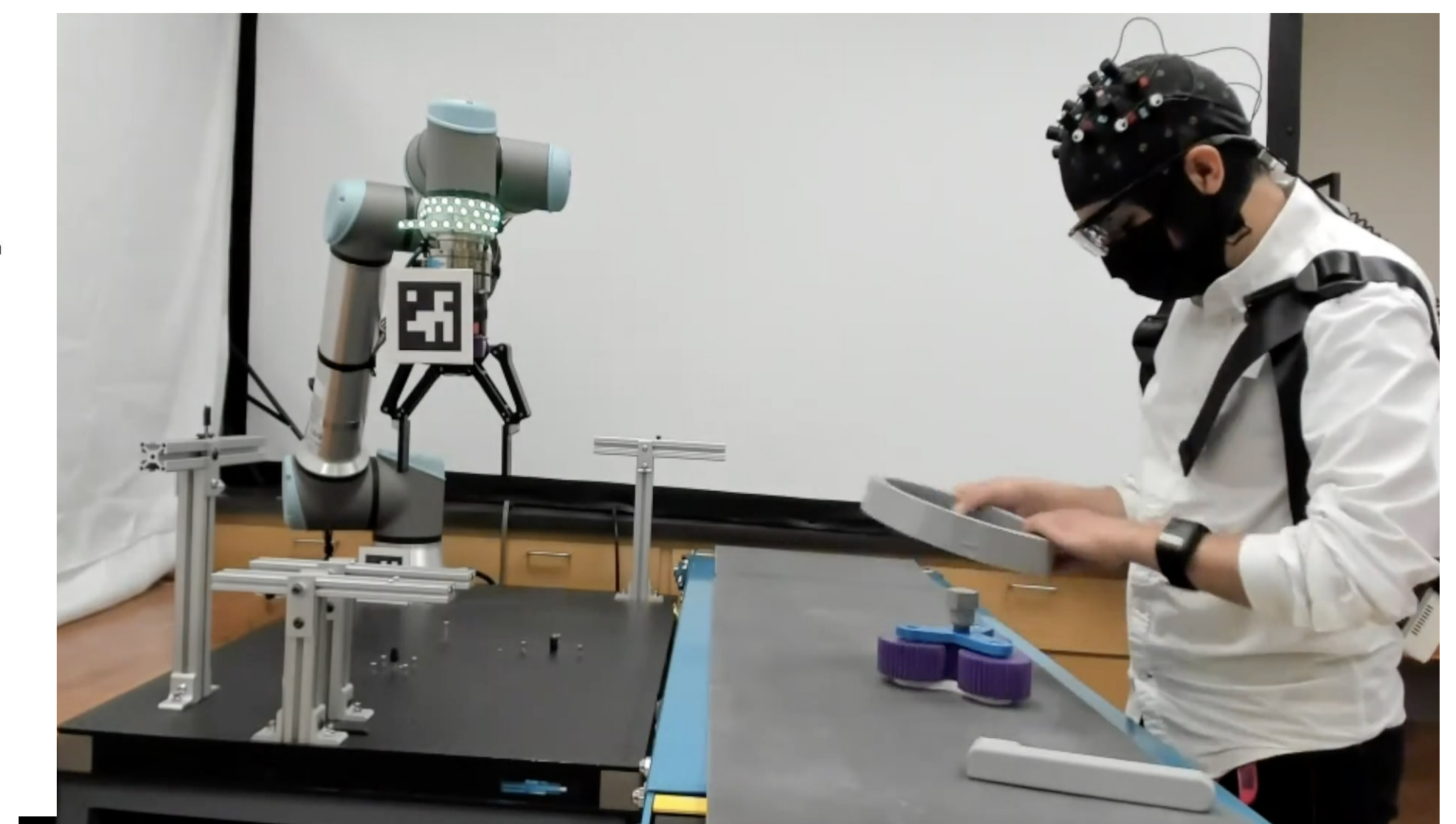
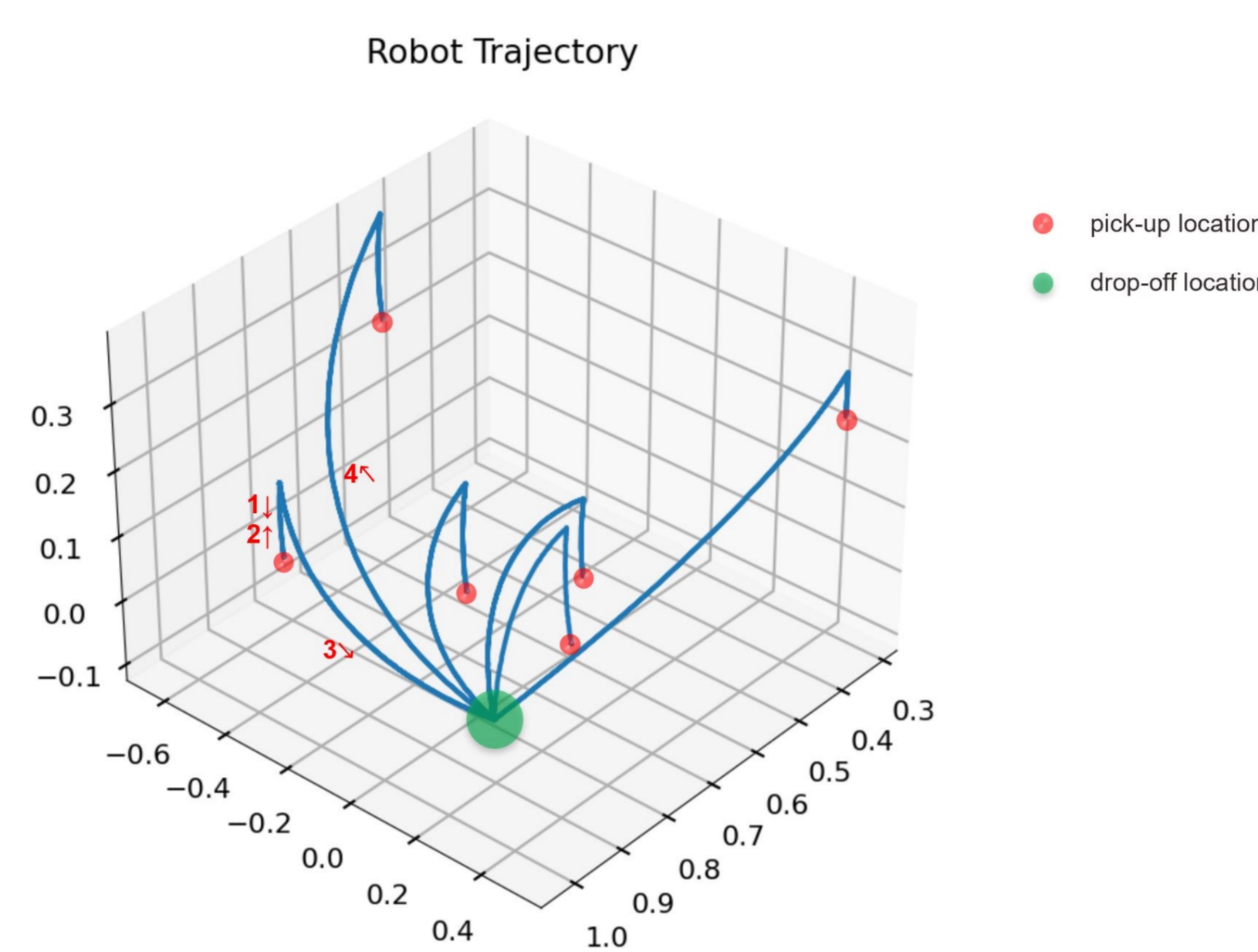
Tobii Glasses 2 (Tobii Pro AB, Sweden)
eye tracker for gaze behavior



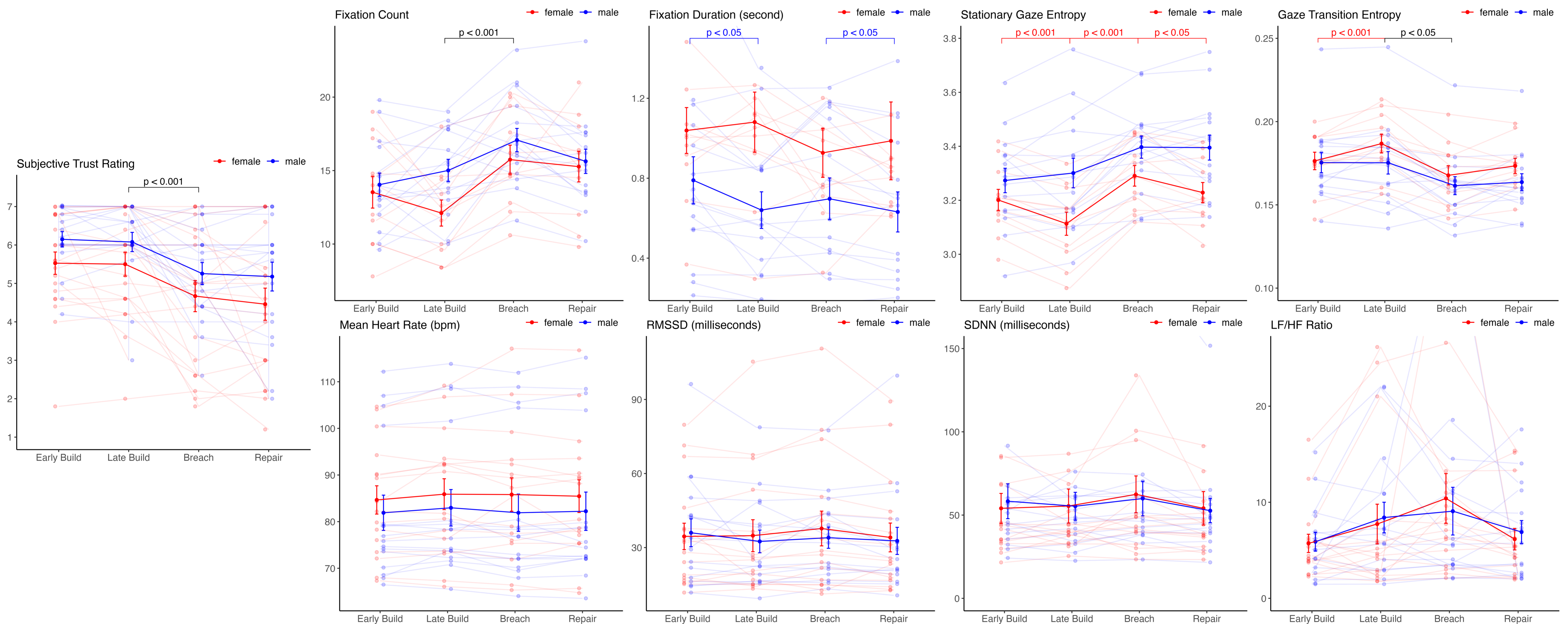
Actiheart 5 (CamNtech, UK) ECG
for physiological indicators

Robot Perturbations

1. Sudden increase in speed to 100% max designed joint speed (120°/Sec.)
2. Sudden loss of speed to 30% max designed joint speed
3. Sudden change in robot indicator light to idle color during operation
4. Invasion of human space while delivering part
5. Variation (± 20 cm) in X and Y drop-off location
6. Providing a part in the incorrect sequence
7. Dropping a part from 30 cm above the workspace



RESULTS



Subjective trust
Heart rate variability
Eye tracking fixation
Eye tracking entropy

Only captured trust breach, with no change during the build and repair phases. No sex differences.
Not sensitive to dynamic trust change, potentially due to complex motor movements.
Decrease in subjective trust was associated with increased fixation counts, reaffirming evidence of the negative relationship between human-automation trust and monitoring frequency [5].
Decreased GTE during the trust breach resembled distrusting behavior [6], supported by decreased trust ratings.
Sex differences – Only males exhibited less automation monitoring during the late build and repair phase; females' unique changes were in entropies throughout the phases.

KEY TAKEAWAYS

- Subjective trust measure was not sensitive to all trust manipulations and additional gaze behavior differences were observed across trust build, breach, and repair phases.
- Gaze behavior is a cognitive outcome, and males & Females demonstrated different cognitive behaviors during trust changes.
- Ultra-short-term HR metrics (<5min) did not capture trust changes, and its sensitivity can be context-based.

REFERENCES

[1] M. Lewis, K. Sycara, and P. Walker, "The Role of Trust in Human-Robot Interaction," in Foundations of Trusted Autonomy, H. A. Abbass, J. Scholz, and D. J. Reid, Eds., in Studies in Systems, Decision and Control, Cham: Springer International Publishing, 2018, pp. 135–159.

[2] J. D. Lee and N. Moray, "Trust, self-confidence, and operators' adaptation to automation," International Journal of Human-Computer Studies, vol. 40, no. 1, pp. 153–184, Jan. 1994, doi: 10.1006/ijhc.1994.1007.

[3] R. Parasuraman and V. Riley, "Humans and Automation: Use, Misuse, Disuse, Abuse," Hum Factors, vol. 39, no. 2, pp. 230–253, Jun. 1997.

[4] J.-Y. Jian, A. M. Bisantz, and C. G. Drury, "Foundations for an Empirically Determined Scale of Trust in Automated Systems," International Journal of Cognitive Ergonomics, vol. 4, no. 1, pp. 53–71, Mar. 2000.

[5] N. Moray and T. Inagaki, "Laboratory studies of trust between humans and machines in automated systems," Transactions of the Institute of Measurement and Control, vol. 21, no. 4–5, pp. 203–211, Oct. 1999.

[6] K. Krejtz et al., "Gaze Transition Entropy," ACM Trans. Appl. Percept., vol. 13, no. 1, pp. 1–20, Dec. 2015.

[7] B. Shiferaw, L. Downey, and D. Crewther, "A review of gaze entropy as a measure of visual scanning efficiency," Neuroscience & Biobehavioral Reviews, vol. 96, pp. 353–366, Jan. 2019.